

Comparison of fabric skins for the simulation of sweating on thermal manikins

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Abstract Sweating is an important thermoregulatory process helping to dissipate heat and, thus, to prevent overheating of the human body. Simulations of human thermo-physiological responses in hot conditions or during exercising are helpful for assessing heat stress; however, realistic sweating simulation and evaporative cooling is needed. To this end, thermal manikins dressed with a tight fabric skin can be used, and the properties of this skin should help human-like sweat evaporation simulation. Four fabrics, i.e., cotton with elastane, polyester, polyamide with elastane, and a skin provided by a manikin manufacturer (Thermetrics) were compared in this study. The moisture management properties of the fabrics have been investigated in basic tests with regard to all phases of sweating relevant for simulating human thermo-physiological responses, namely, onset of sweating, fully developed sweating, and drying. The suitability of the fabrics for standard tests, such as clothing evaporative resistance measurements, was evaluated based on tests corresponding to the middle phase of sweating. Simulations with a head manikin coupled to a thermo-physiological model were performed to evaluate the overall performance of the skins. The results of the study showed that three out of four evaluated fabrics have adequate moisture management properties with regard to the simulation of sweating, which was confirmed in the coupled simulation with the head manikin. The presented tests are helpful for

comparing the efficiency of different fabrics to simulate sweat-induced evaporative cooling on thermal manikins.

Keywords Fabric skin · Thermal manikin · Thermo-physiological simulator · Sweating simulation · Evaporative resistance

Introduction

Sweating is one of the thermoregulatory processes within the human body which is especially important in hot conditions or while exercising. Sweat evaporation contributes to body cooling and preventing the increase of core temperature above values leading to hyperthermia or even heat stroke. Therefore, the heat and mass transfer resulting from sweating is crucial while assessing heat stress.

In nowadays research, sweat-induced evaporative cooling is often simulated with the use of thermal manikins in order to avoid drawbacks of human subject studies such as ethical issues, inter- and intra-subject variability, and high costs. Different sweating simulation methods are applied, such as the following:

- Pre-wetted tight fabric skin put on a dry thermal manikin, e.g., “Tore” (Kuklane et al. 2006)
- Water-filled manikin with a waterproof but vapor-permeable surface, e.g., “Walter” (Fan and Chen 2002)
- Manikin with an inner skin spreading water superficially and an outer vapor-permeable skin, e.g., “Coppelius” (Meinander 1997)
- Manikin with a porous metal surface with superficial sweating, e.g., advanced automotive manikin “ADAM” (Burke and McGuffin 2001)

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- Manikin with a supply of water to a fabric skin by means of sweating outlets distributed over the manikin's surface, e.g., sweating agile manikin "SAM" (Richards and Mattle 2001) and "Newton" (Thermetrics, Seattle, USA)

Phenomena related to sweat evaporation are important in standard tests, such as clothing evaporative resistance (R_{ET}) measurements, e.g., on a sweating guarded hot plate (ISO 1993) and for the evaluation of human thermo-physiological responses to given conditions. Thermal manikin measurements of R_{ET} allow a realistic distribution of the contact area and the air gap between the manikin and the clothing as well as between the layers of garments. According to the test standard (ASTM 2015), all aforementioned sweating simulation methods can be applied. For the assessment of human thermo-physiological responses in hot conditions or for high metabolic rate, a thermal sweating manikin coupled with a mathematical model of human physiology can be used, i.e., a thermo-physiological simulator (e.g., Psikuta et al. 2008; Psikuta et al. 2014). The model and the thermal manikin exchange data in a real-time feedback loop, enabling thermo-physiological predictions based on the real conditions of the experiment, such as environmental parameters and clothing. Thermo-physiological simulators can be useful in many research fields, e.g., clothing research, medical applications, car industry, and indoor thermal comfort research (e.g., Rugh et al. 2004; Foda and Siren 2012; Psikuta et al. 2013; Martínez et al. 2017). The sweating simulation method has to allow dynamic changes of sweat rate; therefore, only manikins with varying water supply rate are used for such coupling (Psikuta et al. 2016).

Until now, the phenomena related to sweat secretion and evaporation have been investigated mostly with regard to standard tests, and the main issues that have been reported in the literature were the following:

- The discrepancy between manikin surface and wet skin surface temperature (Ueno and Sawada 2012; Wang et al. 2010a; Wang et al. 2012; Wang et al. 2010b)
- Different results obtained using the heat loss and mass loss methods (Havenith et al. 2008; Wang et al. 2011) which are both recommended in the standard (ASTM 2015)
- The effect of applying different sweat rates for measurements performed with a constant supply of water to the fabric skin (Lu et al. 2016a)
- The discrepancies associated with the sweating simulation method (Lu et al. 2016b; Wang et al. 2009)

The aforementioned studies mostly focused on tests with a fully wetted skin as the measurements of R_{ET} have to be performed in a saturated state of the fabric and in steady-state conditions. For the simulation of human thermo-physiological responses, however, an investigation of phenomena occurring in all phases of sweating is needed, such

as the onset of sweating, the fully developed sweating, and the drying phase.

Similarly, the desired properties of the fabric skin for sweating simulations are not explicit and ASTM (2015) does not refer to any standard skin for the measurement of R_{ET} . The properties of different fabrics with regard to R_{ET} measurements have been previously investigated for three fabrics, i.e., cotton, blend of cotton and polyester, and polyester (Wang et al. 2015). However, relevant information about the sweating simulation protocol has not been reported, which hinders the interpretation of the results from this study. Additionally, the study focused on measurements with a fully wetted skin and, therefore, all of the fabrics' properties relevant for thermo-physiological transient simulations with wetting and drying phases were not addressed.

In this paper, a detailed study of the moisture management properties of four fabrics typically used as skin has been presented. Basic tests have been conducted to assess the performance of the fabrics in different phases of sweating, i.e., the onset of sweating, fully developed sweating and drying, with the middle phase corresponding to standard R_{ET} measurement. Additionally, measurements with a head manikin coupled to a thermo-physiological model have been conducted in order to evaluate the overall performance of the skins in realistic conditions, including the anatomical shape and the moisture migration phenomena that may influence the sweating simulation.

Methods

Fabrics

Four fabrics were compared to assess their suitability for use as skin for thermal sweating devices, namely, cotton with elastane (CO), polyester (PE), polyamide with elastane (PA), and the skin provided by a manikin manufacturer (Thermetrics, Seattle, USA), referred to as Thermetrics' skin (TH) composed of polyamide and elastane. Cotton and polyamide are used as skins in various research laboratories, the Thermetrics' skin is provided by the manufacturer with the Newton-type manikins, and polyester showed some high wicking properties and was, therefore, selected as a reference fabric. The basic characteristics of the fabrics are listed in Table 1.

Prior to all tests, the fabrics were washed in tap water with soap, rinsed abundantly, and dried, in order to ensure that all samples would be in the same state before the measurements.

Experimental design

The evaluation of skins for the simulation of human thermo-physiological responses consisted of measurements addressing three phases of sweating, namely, the onset of sweating,

Table 1 Basic characteristics of the tested fabrics

Name	Thickness [mm]	Mass per unit area [g/m ²]	Fabric's composition	Manufacturer
CO	0.92 ± 0.03	208 ± 1	95 CO/5 EL	Unknown
cotton with elastane				
PE	0.70 ± 0.01	155 ± 1	100 PE	Comfortrust AG, Switzerland
polyester				
TH	0.66 ± 0.01	195 ± 1	80 PA/20 EL	Thermetrics, Seattle, USA
Thermetrics' skin				
PA	1.08 ± 0.01	226 ± 1	71 PA/29 EL	Salzmann AG, Switzerland
polyamide with elastane				

CO cotton, EL elastane, PE polyester, PA polyamide

fully developed sweating, and drying. Properties concerning the onset of sweating were evaluated by contact angle measurement (hydrophilicity), moisture management test (MMT—wicking effect), and evaluation of water spreading on a vertical surface. For the fully developed sweating, which corresponds to the conditions for R_{ET} measurements, the maximal moisture content (MMC), skin thermal resistance, evaporative cooling efficiency, and the evaporative heat loss for two sweat rates were determined. The drying rate was measured to evaluate the drying properties of the fabrics. Additionally, a simulation of the human thermo-physiological response with a head manikin coupled to a thermo-physiological model has been performed to evaluate the performance of the fabrics in a realistic scenario (Martínez et al. 2017).

For a given thermal sweating device, the surface area of the skin remains unchanged, while the mass of the dry skin differs between fabrics; therefore, the MMC and drying rate values have been related to the unit of surface area. In all measurements, the water was supplied to the back side of the fabrics, which complies with the direction of water supply to skins in thermal sweating devices. The fabric skins for measurements were prepared with a 10% stretch typically used in thermal sweating devices to ensure good contact.

Whenever the supply of water of a thermal device was used, the experiments were carried out using Nanopure water in order to prevent clogging of the sweating system. However, tap water was used in experiments with pre-wetted skin, similarly to the experimental protocol presented by Wang et al. (2010a, 2012, 2016) and Lu et al. (2016b).

Contact angle measurement

Three samples of 1 × 1 cm of each fabric were conditioned for 12 h at air temperature 20 ± 0.5 °C, relative humidity 65 ± 5%, and air speed <0.1 m/s. Each sample was placed in a well plate insert (Fig. 1a), which provided a flat and slightly stretched fabric's surface. The measurements were performed using a contact angle measuring system (DSA25, Krüss GmbH,

Germany) with dedicated software allowing the calculation of contact angles.

Moisture management tests (MMT)

Five circular samples (Φ 80 mm) of each fabric were conditioned for 12 h at air temperature 20 ± 0.5 °C, relative humidity 65 ± 5%, and air speed <0.1 m/s. The measurement principle has been described in the literature (Hu et al. 2005; Yao et al. 2006). The following parameters for the top and bottom surface of the fabrics were measured in a moisture management tester (M290MMT, SDL Atlas, USA): wetting time, maximum wetted radius, moisture spreading speed, and accumulative one-way transport capacity. The tests were performed with water supplied in the direction of the gravitational force.

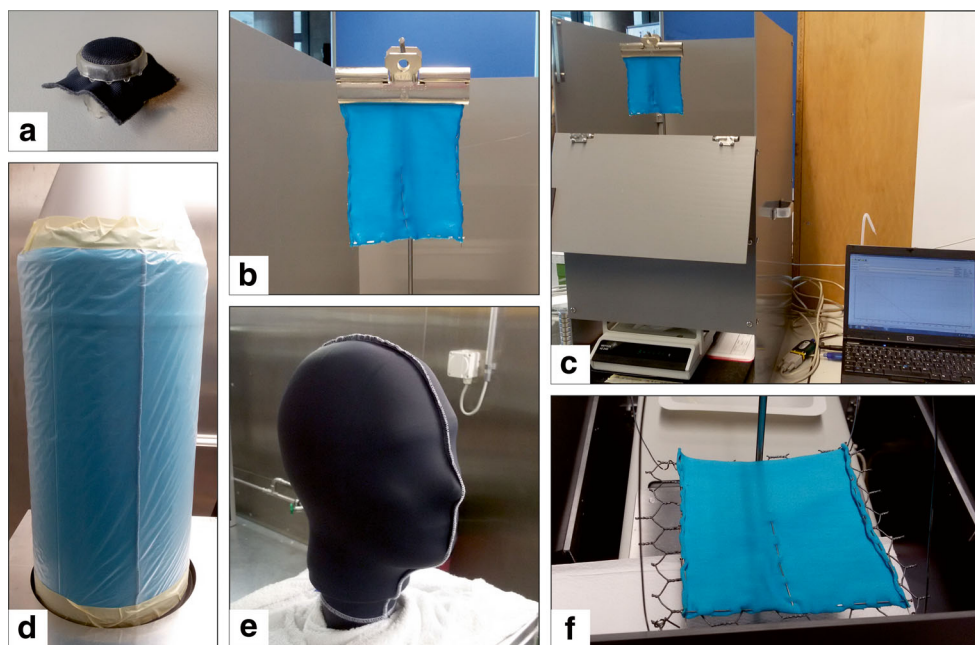
Water spreading on a vertical surface

The MMT allows only testing samples placed horizontally, while most of the surface of thermal manikins is vertical; therefore, a visual analysis of water spreading was performed on the heated sweating cylinder Torso (Annaheim et al. 2015; Zimmerli and Weder 1997). A single sweating outlet was set to sweat for 60 s which resulted in 1.35 ± 0.05 g of water delivered to the skin. Pictures of the wetted skin were made after 60 s of sweating and after additional 60 s without sweating. The wetted area and wetting ranges were calculated in a dedicated software (AutoCAD, Autodesk, USA) after manually redrawing the contours of the wet surfaces.

Maximal moisture content per unit area (MMC)

One sample of each fabric (10 × 10 cm) was conditioned in dry state for 12 h at air temperature 21 ± 0.7 °C, relative humidity 70 ± 5%, and air speed <0.1 m/s, pinned at the edges to avoid rolling of the fabric when wetted and weighted (Fig. 1b). The pinned samples were then submerged in tap water at room temperature for at least 1 h before the

Fig. 1 **a** Sample for contact angle measurement. **b** Sample hung vertically with pins during MMC measurement. **c** MMC experimental setup. **d** Skin with foil covering taped to the heated guards of Torso for total thermal resistance measurement. **e** Skin for head manikin tests. **f** Sample on a horizontal wire net during drying rate measurement



measurement. The experimental setup consisted of a stand with a hook placed on an analytical balance (Mettler AE240, Mettler-Toledo, Switzerland) with continuous recording of the mass loss (Fig. 1c). The sample was hung vertically with a clamp, and the whole setup was encased to impede the influence of air movement on the mass measurement. As the sample was soaked with water, droplets were forming on the lower end of the sample and were falling, which resulted in a decrease of the mass of the sample. The MMC was calculated based on the mass of the wet sample after the last droplet of water has been observed to drip, according to the following equation:

$$\text{MMC} = \frac{m_{\text{wet}} - m_{\text{dry}}}{A} \left(\frac{\text{g}}{\text{m}^2} \right), \quad (1)$$

where m_{wet} and m_{dry} are the mass of the sample in wet and dry state (g), respectively, and A is the surface area of the sample (m^2).

The measurements were repeated five times for each fabric and average MMC was calculated.

Skin thermal resistance

The thermal resistance properties of the fabric skins were measured on the heated sweating cylinder Torso in dry and wet conditions. The measurements were performed in a climate chamber at air temperature 20 ± 0.5 °C, relative humidity $50 \pm 5\%$, and air speed <0.1 m/s, logged by microclimate sensors (Sensoanemo 5100CL, Sensors Electronic, Poland). The amount of tap water contained in the fabrics to achieve a fully saturated wet skin on Torso without dripping has been

empirically assessed to be smaller than the MMC (i.e., 62, 63, 67, and 87% of the MMC for PE, PA, TH, and CO, respectively). This was due to the stretching of the fabrics and the necessary manipulation of the skins while putting them on Torso. The wetted skins were sealed in plastic bags and conditioned in the climate chamber for 12 h to ensure homogeneous moisture distribution in the fabrics. The surface temperature of Torso was set to 35 °C. Heat flux values were logged for 1 h, and three repetitions were performed for each fabric in three states: dry skin only, dry skin with additional plastic foil, and wet skin with additional plastic foil, from which total thermal resistances R_{dry} , $R_{\text{dry+foil}}$, and $R_{\text{wet+foil}}$ were calculated based on the mean heat flux value from 20 min steady-state period according to the following equation:

$$R = \frac{(T_{\text{Torso}} - T_{\text{air}})}{\text{HF}} \left(\frac{\text{m}^2\text{K}}{\text{W}} \right), \quad (2)$$

where T_{Torso} is the mean surface temperature of Torso (°C), T_{air} is the mean air temperature (°C), and HF is the mean heat flux on Torso (W/m^2).

The plastic foil covering was taped to the heated guards to prevent evaporation of moisture during the wet skin measurements (Fig. 1d). In these conditions, the moisture can evaporate from the fabric and condense on the inner side of the foil, which leads to an increase of the foil temperature (Havenith et al. 2008). Therefore, thermal resistance determined in such conditions is called the apparent wet thermal resistance (Lotens et al. 1995; Wang et al. 2016). From the two measurements with dry skin, the thermal resistance of the foil R_{foil} (Eq. 3) and then the apparent thermal resistance of the wet skin and the

adjacent air layer without the foil R_{wet} (Eq. 4) were calculated as follows:

$$R_{\text{foil}} = R_{\text{dry+foil}} - R_{\text{dry}} \left(\frac{\text{m}^2\text{K}}{\text{W}} \right) \quad (3)$$

$$R_{\text{wet}} = R_{\text{wet+foil}} - R_{\text{foil}} \left(\frac{\text{m}^2\text{K}}{\text{W}} \right) \quad (4)$$

Evaporative cooling efficiency

The measurements were performed following the test protocol and equations by Havenith et al. (2008) in a climate chamber with air temperature equal to 34.1 ± 0.2 °C, relative humidity equal to $18 \pm 5\%$, i.e., water vapor pressure equal to 1 kPa, and air speed lower than 0.2 m/s. Each skin was wetted with tap water as described for wet skin thermal resistance measurements and conditioned in sealed bags in the climate chamber for at least 12 h. The measurements were performed both on Torso and on a nine-zone head manikin (Martínez et al. 2017, Thermetrics, Seattle, USA; Fig. 1e) in the so-called isothermal conditions where $T_{\text{air}} = T_{\text{Torso}} = T_{\text{head manikin}}$. After putting the wet skin on the thermal device, an immediate increase in the heat flux values was observed after which a steady-state measurement of evaporative heat loss was possible for at least 15 min before a sharp decrease in heat flux value was observed when the skin started to dry out. On the head manikin, it was not possible to obtain a steady-state with pre-wetted skin due to fast drying out of the upper zones related to gravitational moisture migration. Therefore, constant but individual flow set points for each zone have been empirically selected in a way that prevented skin drying out and any dripping and were as follows: forehead 310 ml/m² h, face 300 ml/m² h, left and right temple 420 ml/m² h each, crown 330 ml/m² h, upper head 270 ml/m² h, lower head 220 ml/m² h, occipital 250 ml/m² h, and neck 200 ml/m² h, resulting in 0.66 g/min of water delivered to the entire head.

Apart from heat flux measurements, also the mass loss rate was monitored by continuous weighing of the thermal device with the skin (Mettler-Toledo, Switzerland). For each fabric, three repetitions have been performed on Torso and five on the head manikin and mean values were calculated.

Since the measurements have been carried out in the so-called isothermal conditions (Havenith et al. 2008), the total real heat loss E_{real} observed was attributed to evaporation, i.e., no dry heat loss occurred. The evaporative cooling potential E_{mass} has been calculated as the latent heat content of the water that was evaporating from the skin.

$$E_{\text{mass}} = \dot{m} \times \lambda \left(\frac{\text{W}}{\text{m}^2} \right), \quad (5)$$

where \dot{m} is the mass loss rate (g/m² s), λ is the enthalpy of evaporation, $\lambda = 2420$ J/g (for $T_{\text{air}} = 34$ °C).

The real evaporative cooling efficiency η_{real} has been calculated according to the following equation:

$$\eta_{\text{real}} = \frac{E_{\text{real}}}{E_{\text{mass}}} \times 100\% \quad (6)$$

Evaporative heat loss on the head manikin

The tests were performed in a climate chamber at air temperature 25 ± 0.3 °C, relative humidity $50 \pm 5\%$, and air speed <0.1 m/s, logged by microclimate sensors (Sensoanemo 5100CL, Sensors Electronic, Poland). The surface temperature of all head zones was set to 35 °C. The measurement for each skin consisted of five 1-h phases, such as dry phase, wet phase with sweat rate of 250 ml/m² h (0.58 g/min for the entire head), dry phase, and wet phase with sweat rate of 500 ml/m² h (1.15 g/min for the entire head). This alternation of dry and wet phases made it possible to obtain a steady-state at the end of each phase of the measurement for at least 15 min. During the measurements, surface temperatures and heat fluxes for each zone were logged with the manikin's software (ThermDAC, Thermetrics, Seattle, USA). The measurements for each fabric were repeated three times, and the evaporative heat loss was calculated as the difference between average heat loss from steady-state in wet and dry conditions.

Drying rate

Samples for drying rate tests underwent the same conditioning process as for MMC tests and were performed on a slightly modified experimental setup with a wire net allowing horizontal hanging of the samples (Fig. 1f), which ensured homogeneous drying of the entire surface of the fabric, in contrast to vertical hanging where the moisture gravitationally migrated to the lower end of the sample. The mass of the sample was recorded every 5 s until the fabric was dry, i.e., the mass was equal to the dry mass of the sample before wetting. Linear regression was applied to the recorded mass measurements to calculate the drying rate ($R^2 > 0.99$). For each fabric, three repetitions were performed, from which the average value of drying rate was calculated.

Simulation with the head manikin coupled to a thermo-physiological model

In order to compare the performance of the fabric skins while simulating the human thermo-physiological response to an exposure, measurements were performed with a coupled system consisting of the head manikin and the model of human thermo-physiology by Fiala (Fiala and Havenith 2015, Martínez et al. 2016, Martínez et al. 2017, Psikuta et al. 2012; FPCm.5.3, Ergosim, Germany). A real-time feedback

loop allowed the head manikin to be controlled by the physiological model, where the model was providing local surface temperatures and sweat rates for the head according to the real heat loss from the manikin surface, and the remaining body parts were simulated purely virtually. The coupling has been described in detail by Martínez et al. (2017).

For this study, one experimental trial has been chosen, and coupled simulation tests were performed with all four skins in order to compare their reliability in reproducing experimental data from a human subject study. The experimental trial consisted of a pre-exercise standing phase (20 min), a cycling phase (first 3 min with a metabolic rate of 2.5 met, then 45 min with 5.3 met), and a post-exercise standing phase (15 min). The experimental conditions for the coupled simulation test have been described in detail by Martínez (2015, see Table 5.9 exposure 25). Three repetitions of the coupled simulation with each skin have been performed, and mean values of forehead temperature and sweat rate have been calculated.

Since the internal sweating system of the head manikin and the environmental conditions were the same in all measurements, the differences for forehead temperature and sweat rate between the four skins can be attributed to the different properties of the fabrics. To evaluate the performance of the skins, statistical indices such as root mean square deviation (rmsd) and bias of forehead temperature have been computed, according to the following equations (Psikuta et al. 2013):

$$\text{rmsd} = \sqrt{\frac{\sum (t_{\text{measured}} - t_{\text{predicted}})^2}{n}} \quad (7)$$

$$\text{bias} = \frac{\sum (t_{\text{measured}} - t_{\text{predicted}})}{n}, \quad (8)$$

where t_{measured} is the measured forehead temperature from experiment, $t_{\text{predicted}}$ is the forehead temperature predicted by the coupled system, and n is the number of experimental data points.

Results

The results for the measurements of contact angle, MMT, water spreading on a vertical surface, MMC, thermal resistance, evaporative cooling efficiency, drying rate, and evaporative heat loss from the head manikin are presented in Table 2. The water spreading on Torso is also presented in Fig. 2. The results from the simulations with the head manikin coupled to the thermo-physiological model are shown in Fig. 3 together with experimental values and pure physiological simulation values.

The measurement of contact angle for CO, PE, and TH was not possible, since the water was absorbed very fast and contact angle measurement was not possible to record by the

measuring system. Therefore, these three fabrics can be assumed to be highly hydrophilic. The contact angle value for PA (131.2°) corresponds to a mostly non-wetting, hydrophobic fabric (de Gennes et al. 2004).

Discussion

Onset of sweating

Besides PA, the tested fabrics showed good performance in tests related to the onset of sweating. The hydrophilicity of CO, TH, and PE revealed in the contact angle measurement was confirmed in the MMT measurements with *fast* and *very fast* wetting times and moisture spreading speeds (Table 2). The values of bottom and top wetted radii which were assessed as *large* and *very large*, and high moisture spreading speed for these three fabrics are beneficial for the simulation of human-like sweating, i.e., when no pre-wetting is used. High standard deviation values from MMT tests of the PA fabric are related to the nonuniform wetting of the fabric due to its hydrophobicity which led to non-repeatable measurements, e.g., different shape and dimensions of the wetted area.

Since thermal manikins used with a fabric skin have a significantly inferior number of sweating outlets to human skin, good moisture spreading properties ensure a superficial wetting, as opposed to a more punctual liquid delivery if a hydrophobic fabric was used. Liquid spreading properties are of particular importance for the first phase of sweating as the cooling effect of sweating can only be fully measured once the moisture reaches the neighboring sensors embedded in the surface of the thermal device. If the wetted radius is too small, only negligible changes in heat loss will be measured, although some cooling will occur locally leading to inaccurate predictions from the physiological model during coupled simulations, which was reported by Psikuta et al. (2008) for the simulation of a warm exposure with low sweat rate.

The measured accumulative one-way transport capacity R represents the ability of the fabric to wick moisture from the inner to the outer surface. The low value for CO, i.e., 6% and the negative values for PE and TH, i.e., −68 and −70% (Table 2) show that the moisture stays partially near the heated surface of the sweating device, which might be a desirable property of skins for sweating simulations. It has been shown by Havenith et al. (2013) that the evaporative cooling efficiency decreases when the evaporation occurs farther away from the thermal device. Therefore, a poor accumulative one-way transport capacity might impede the migration of moisture towards clothing layers and as such provide more cooling at the surface of the manikin. However, in vertical orientation of the skin on the manikin, this effect might be lower than observed in this test, where the sample was oriented horizontally.

Table 2 Summary of results (average value \pm standard deviation)

	Test	Unit	CO	PE	TH	PA
1	Contact angle	Deg	–	–	–	131.2 \pm 5.5
		Class	Hydrophilic	Hydrophilic	Hydrophilic	Hydrophobic
2	MMT					
2.1	WT _T	s	3.5 \pm 0.1	2.8 \pm 0.1	2.6 \pm 0.2	20.3 \pm 20.9
		Class	Fast	Very fast	Very fast	Slow
2.2	WT _B	s	3.6 \pm 0.1	3.0 \pm 0.1	2.8 \pm 0.3	8.9 \pm 1.5
		Class	Fast	Fast	Very fast	Medium
2.3	MWR _T	mm	20 \pm 0	26 \pm 2	30 \pm 0	21 \pm 7
		Class	Large	Very large	Very large	Large
2.4	MWR _B	mm	20 \pm 0	26 \pm 2	30 \pm 0	22 \pm 8
		Class	Large	Very large	Very large	Large
2.5	SS _T	mm/s	3.2 \pm 0.1	5.1 \pm 0.4	7.0 \pm 0.8	1.9 \pm 1.5
		Class	Fast	Very fast	Very fast	Slow
2.6	SS _B	mm/s	3.1 \pm 0.1	4.9 \pm 0.3	6.9 \pm 0.8	2.4 \pm 1.9
		Class	Fast	Very fast	Very fast	Medium
2.7	R	%	6 \pm 25	–68 \pm 3	–70 \pm 8	115 \pm 147
		Class	Fair	Poor	Poor	Good
3	Moisture spreading on a vertical surface					
3.1	WA ₆₀	cm ²	37.4	55.2	51.4	15.9
3.2	WA ₁₂₀	cm ²	52.6	93.4	67.9	19.2
3.3	WA ₁₂₀ /WA ₆₀	–	1.4	1.7	1.3	1.2
3.4	WR upwards	cm	3.4	3.0	1.6	1.0
3.5	WR downwards	cm	4.2	7.5	3.7	5.0
3.6	WR sideways ^a	cm	3.1	3.5	6.0	2.2
4	MMC	g/m ²	480 \pm 7	485 \pm 12	492 \pm 21	577 \pm 2
5	Isolative properties					
5.1	R _{dry}	m ² K/W	0.109 \pm 0.002	0.118 \pm 0.002	0.103 \pm 0.001	0.114 \pm 0.001
5.2	R _{wet}	m ² K/W	0.081 \pm 0.002	0.089 \pm 0.004	0.081 \pm 0.003	0.085 \pm 0.006
5.3	R _{wet} /R _{dry}	%	74.8 \pm 2.0	75.3 \pm 3.1	79.0 \pm 3.3	75.1 \pm 5.9
6	Evaporative cooling efficiency					
6.1	Torso	%	80.1 \pm 3.0	87.4 \pm 0.3	79.8 \pm 4.0	86.1 \pm 1.9
6.2	Head manikin	%	80.1 \pm 3.4	81.0 \pm 4.8	81.3 \pm 2.8	79.5 \pm 3.5
7	Drying rate	g/m ² h	83.4 \pm 1.6	82.6 \pm 0.9	89.0 \pm 1.7	83.6 \pm 1.2
8	Evaporative heat loss head manikin					
8.1	For 250 ml/m ² h	W/m ²	138.5 \pm 25.4	159.4 \pm 14.5	158.1 \pm 20.4	111.1 \pm 17.9
8.2	For 500 ml/m ² h	W/m ²	216.6 \pm 1.6	202.8 \pm 3.1	222.1 \pm 4.8	105.5 \pm 9.5

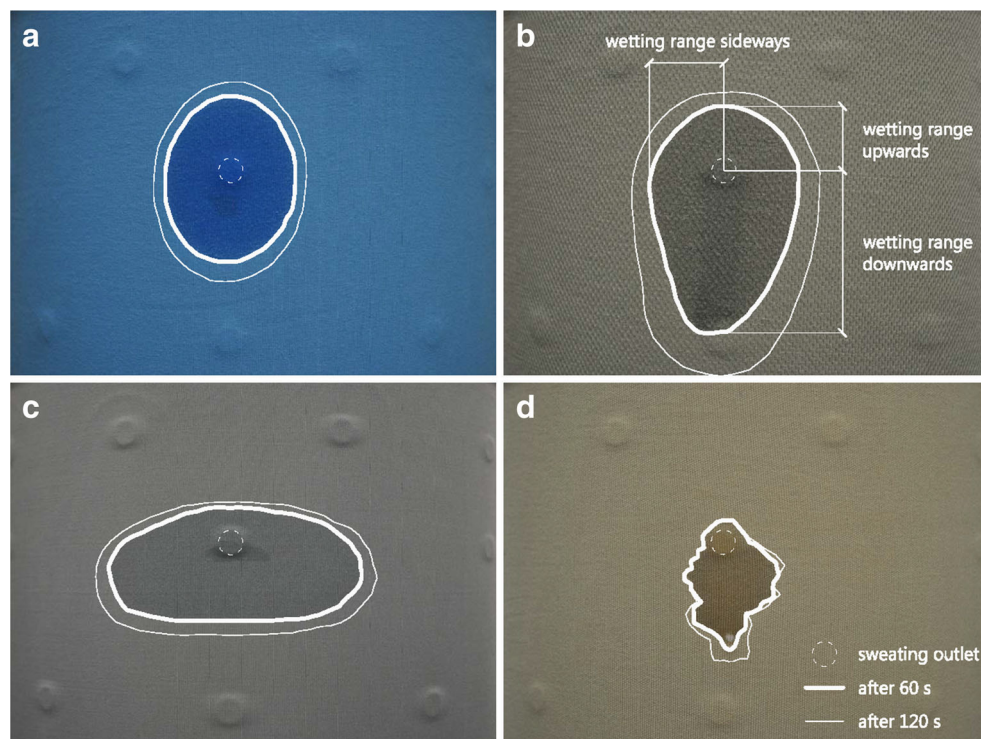
CO cotton with elastane, PE polyester, TH Thermetrics' skin, PA polyamide with elastane, MMT moisture management test, class classification, WT_T, WT_B wetting time of top and bottom surface, MWR_T, MWR_B maximum wetted radius of top and bottom surface, SS_T, SS_B moisture spreading speed of top and bottom surface, R accumulative one-way transport capacity, WA₆₀, WA₁₂₀ wetted area after 60 and 120 s, WR wetting range, MMC maximal moisture capacity per area, R_{dry}, R_{wet} total thermal resistance of the skin with adjacent air layer in dry and wet conditions

^a Mean value from the left and right WR

Thermal sweating devices, such as cylinders and body-part or full-body manikins, have mostly vertical surfaces; therefore, the measurements on Torso provided valuable information on the vertical moisture spreading. Poor liquid spreading in the PA skin was confirmed; the water supplied to the fabric was passing through it and rolling off without wetting the skin

(Fig. 2d). For CO, PE, and TH, the wetted area had noticeably different shapes, although all three fabrics showed similar performance during MMT measurements (Fig. 2a–c). This indicates that the skin and the thermal sweating manikin should match each other, i.e., the skin properties ought to ensure enough water spreading for a specified number and location

Fig. 2 Moisture spreading on a vertical surface after 60 s with wetting and additional 60 s without wetting for fabrics **a** cotton CO, **b** polyester PE, **c** Thermetrics' skin TH, and **d** polyamide PA

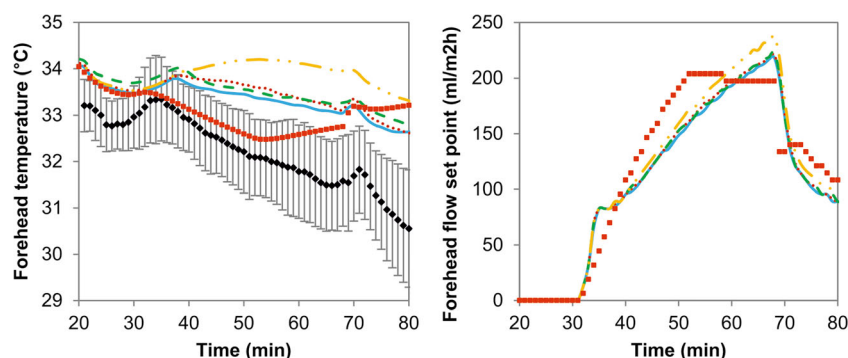


of sweating outlets. For example, for an efficient wetting of the TH skin, the horizontal distance between outlets can be much bigger due to a higher lateral wetting range, but the vertical distance should be smaller than for the other tested fabrics (Table 2, Fig. 2). To avoid moisture migration and dripping of water, fabrics with lower downward wetting range should be chosen for R_{ET} measurements, i.e., CO or TH (Table 2).

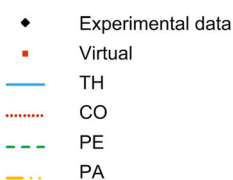
The contact angle and moisture spreading on a vertical surface evaluation can be recommended as valuable

measurements for the evaluation of fabrics' properties related to the initial phase of sweating. Checking the hydrophilicity of any fabric by measuring the contact angle is a fast and efficient way of determining whether a fabric could be suitable for use as a skin. The example of TH and PA fabrics, which had utterly different wetting properties despite a similar fabric's composition (Table 1), shows that it is not possible to evaluate the properties of a skin based only on its fiber content. Fabric tightness (Yanilmaz and Kalaoğlu 2012) and finishing treatment play also an important role and their resultant effect can

Fig. 3 Forehead temperature and flow set point: experimental data from exposure, values from virtual simulation, i.e., with physiological model only, and from coupled simulations with all four skins; for forehead temperature, the rmsd and bias values are presented



	rmsd	bias
Virtual	1.11	-0.87
TH	1.23	-1.15
CO	1.35	-1.26
PE	1.40	-1.33
PA	1.83	-1.66



be summarized by contact angle measurement. For the water spreading properties of fabrics, the evaluation on a vertical setup provides more valuable and realistic information for manikins' skins, since the manikins' surfaces are mostly vertical.

Fully developed sweating

In the case of simulation of thermo-physiological responses, the MMC value can be interpreted only for fabrics with good moisture spreading properties, since the full wetting of the skin is otherwise unlikely, e.g., in the case of PA skin the MMC equal to 577 g/m^2 may not be possible to reach without pre-wetting of the fabric (Table 2). Berglund (1971) calculated the critical thickness of water layer on the human body above which dripping occurs to be $37.6 \text{ }\mu\text{m}$, i.e., 37.6 g/m^2 of body surface. However, data were collected only from one subject. Also, the water trapped inside the fabric does not behave in the same way as sweat in the form of droplets on the human skin and, therefore, the critical thickness of water layer given by Berglund (1971) cannot be directly compared to the MMC values for the tested fabrics.

It has been shown by Wang et al. (2016) that the more moisture added to clothing, the smaller the apparent wet thermal insulation. Therefore, the skin thermal resistance during thermo-physiological simulation with a thermal manikin can vary between its maximal dry value and the wet skin insulation value. For the tested fabrics, the apparent thermal resistance of wet skins decreased by 25% for CO, PE, and PA and by 21% for TH in comparison to the value for dry skin (Table 2). The knowledge about thermal resistance of the fabrics in both dry and wet state may contribute to the development of coefficients to include in thermo-physiological model's predictions, in order to take into account the additional insulation resulting from the skin while carrying out coupled simulations, especially for low sweat rates.

The evaporative cooling efficiency measurements showed differences between the evaporative heat loss determined by the heat loss and mass loss methods for all four tested fabrics (Table 2). As described in the literature (Burton 1944; Wang et al. 2011), some of the heat for evaporation is taken from the environment, leading to the discrepancies between the two calculation methods. In the measurement performed on Torso, PA and PE skins showed a higher evaporative cooling efficiency than CO and TH fabrics, i.e., 86 and 87% for PA and PE and 80 and 82% for CO and TH (Table 2). However, the measurements performed on the head manikin led to similar values for all four tested skins, i.e., approximately 80% of evaporation heat taken from the head manikin and 20% from the environment (Table 2). The evaporative cooling efficiency values obtained from measurements on the head manikin are comparable with the one presented by Havenith et al. (2008) for an impermeable ensemble, that is approximately 80–85%

and by Lu et al. (2016a) for a wet skin only, which equaled 85%. The results from Wang et al. (2011) for a wet skin only were lower, i.e., 73%. It has to be noted, however, that the measurement conditions were not the same in all of these studies. The reason for the observed discrepancies in evaporative cooling efficiency values on Torso and on the head manikin for two fabrics, i.e., PE and PA, may be due to different sweating simulation methods, i.e., pre-wetting of the skin for Torso measurements and pre-wetting with additional constant moisture delivery to the skin for the measurements on the head manikin. When no additional water is supplied to the skin during the test, the real water vapor pressure at the skin surface may differ from the one assumed for fully saturated fabric, which was described by Lu et al. (2016b). These discrepancies may have been more pronounced in the case of PE and PA skins due to the fabrics' individual properties. Additionally, the shape of Torso allowed a full contact of the skin with the device, whereas less contact was ensured on the head manikin due to the anatomical shape of the device.

The mean evaporative heat loss on the head manikin for a low flow set point, i.e., $250 \text{ ml/m}^2 \text{ h}$, had a high standard deviation for all tested fabrics, corresponding to high values of the coefficient of variation, i.e., ranging from 9% for PE to 18% for CO (Table 2). The lower repeatability of these measurements might have been caused by the fact that only some of the sensors embedded in the manikin surface could detect the increased heat loss due to evaporative heat and even small differences in the wetted area shape between the repetitions could affect the measured values. The evaporative heat loss measurements for a sweat rate of $500 \text{ ml/m}^2 \text{ h}$ had higher repeatability for the individual fabrics (Table 2). The low and comparable values of evaporative heat loss for both flow set points in the case of the PA skin, i.e., 111.1 and 105.5 W/m^2 , are a consequence of the hydrophobicity of the fabric which caused a limited wetting of the skin.

For the evaluation of fabrics or the development of new fabrics for use as a sweating skin, the measurements of MMC, cooling evaporative resistance, and isolative properties are suggested as relevant tests of the properties related to the fully developed phase of sweating.

Drying phase

For simulations with lower sweat rates, i.e., when all the supplied water would stay trapped inside the skin and no dripping would occur, the drying rate provides direct information about the drying time of each fabric. However, the drying time of fully wetted skins depends also on their MMC, i.e., the mass amount of water to evaporate varies between fabrics. For instance, the drying rates of CO and PA were found to be very similar, i.e., 83.4 and $83.6 \text{ g/m}^2 \text{ h}$, but when fully wetted the CO skin would dry faster due to a 23% smaller MMC than the PA fabric (Table 2).

In the case of standard R_{ET} measurements with a pre-wetted skin, a combination of high MMC and low drying rate is beneficial to obtain longer steady-state heat flux measurement. Therefore, the PA fabric has better drying properties for R_{ET} measurement than the other three fabrics (Table 2). This advantage only applies for pre-wetted skin as the water spreading properties of the PA skin have been found to be poor.

Coupled simulation with wetting and drying phases

The coupled simulation performed with the head manikin controlled by the thermo-physiological model permitted to evaluate the suitability of the fabrics for simulating a realistic sweating scenario. The accuracy of the coupled simulation in reproducing the forehead temperature was influenced by three factors, namely, the accuracy of the pure virtual simulation, the environmental conditions during the exposure, and the properties of the fabric skin. During the coupled simulation, the thermo-physiological model and the environmental conditions were not modified, with the skins being the only changing factor. It can be seen in Fig. 3 that the use of CO, PE, and TH skin led to similar forehead temperature and sweat rate distribution for the simulated scenario. The inadequacy of PA for use as a skin demonstrated in the basic tests was confirmed by the higher rmsd value and the higher temperature and sweat rate predictions. However, more examples of such coupled simulations could confirm the good performance of the CO, PE, and TH skins.

In the pure virtual simulation, it is assumed that 100% of latent heat is taken from the body surface. However, the cooling efficiency tests showed that around 80% of heat was taken from the surface of the head manikin, with the remaining 20% being taken from the surrounding environment (Table 2). This is why the forehead temperature was higher for the coupled simulation than in the case of pure virtual simulation in the developed phase of sweating (Fig. 3, after approx. 40 min).

Conclusions

The properties of fabrics to be used as a skin for thermal sweating devices such as manikins have been investigated in basic tests with respect to three phases of sweating, namely, the onset of sweating, fully developed sweating, and drying phase. Overall, the CO, PE, and TH fabrics showed a similarly good performance related to tests with a thermo-physiological human simulator and can be, therefore, recommended for use with thermal sweating manikins. However, the fabric should always be chosen to match the sweating system of the manikin itself, e.g., the spacing between sweating outlets, to ensure that the moisture spreading properties will allow for efficient skin

wetting. The CO fabric showed the best properties for R_{ET} measurements, i.e., low downward wetting range and desired combination of MMC and drying rate. Also, the use of PA for R_{ET} measurements with pre-wetted skin could be considered due to its high MMC and low drying rate, although the poor wetting properties of this fabric hinder its use in measurement with gradual sweating.

The study shows the different requirements for skins for R_{ET} measurements and for the simulation of human thermophysiological responses. The presented tests form a methodology for comparing different fabrics to be used as a sweating skin. Moreover, the discussion of various properties of skins can be useful for the development of new fabrics suitable for sweating simulations.

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Compliance with ethical standards

Conflict of interest The authors declare that they have no conflict of interest.

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